



Networking Algorithms

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[Project: Dynamic Sensor Nets (ISI-East)]





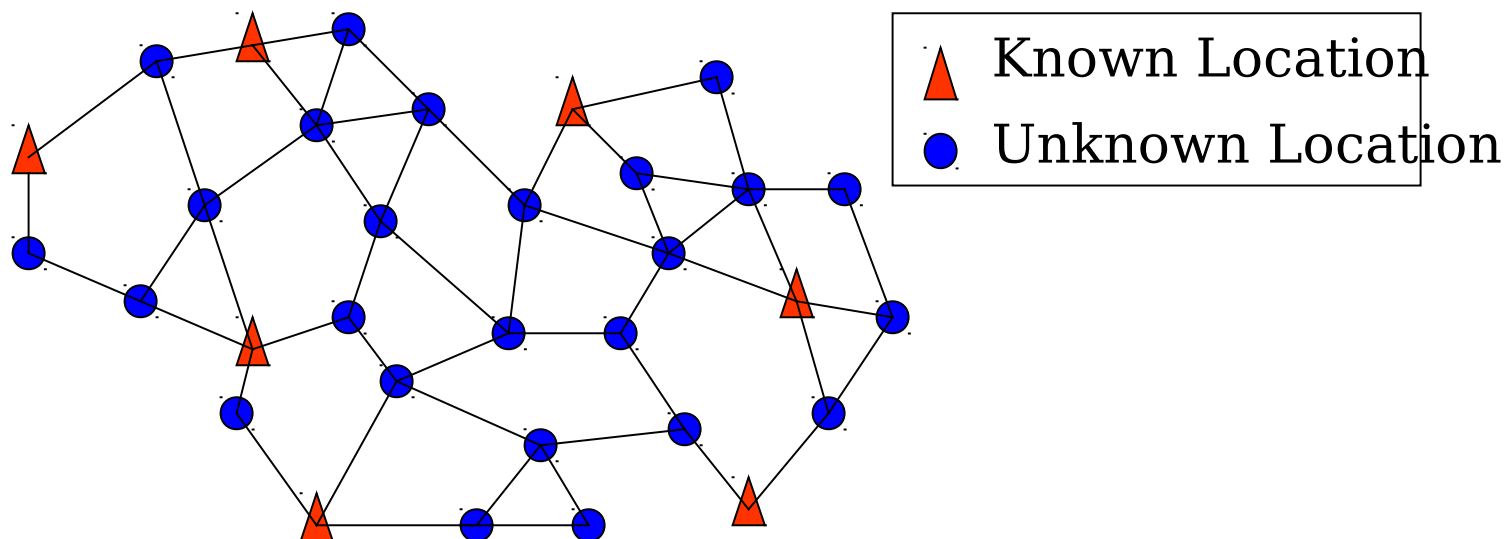
Outline

- I. Dynamic location discovery**
- II. Topology management**
- III. Dynamic MAC address assignment**



I. Dynamic Location Discovery

- **Discovery of absolute and relative location important**
 - Location-based naming and addressing, geographical routing, tracking
- **GPS not enough**
 - LOS-requirements, costly, large, power-hungry
- **Ad hoc precludes trilateration with special high power beacons**
 - also, susceptible to failure
- **Problem: given a network of sensor nodes where a few nodes know their location (e.g. through GPS) how do we calculate the location of the other nodes?**



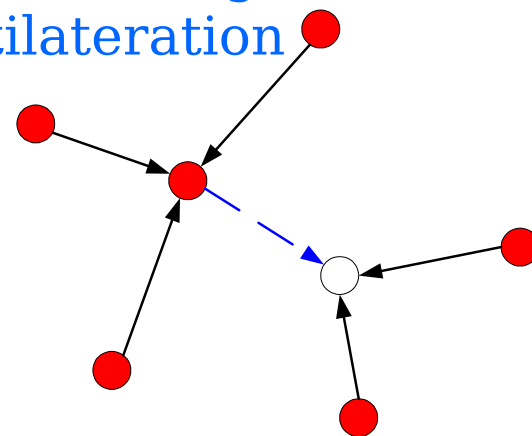


Ad-Hoc Localization System (AHLoS)

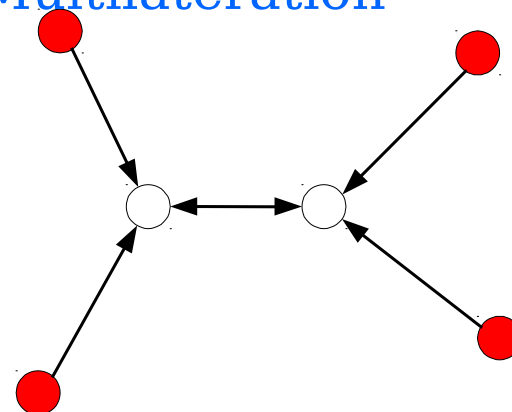
GOALS

- **Localization in a distributed fashion**
- **Trade-offs**
 - Robustness
 - Computation vs. communication
- **Ranging using Ultrasound**
- **Integrated with routing messages**
 - Location discovery almost free
- **Implementation**
 - Ranging using radio-synchronized ultrasound
 - 3m range, noisy
 - Accuracy:
 - Iterative: ~ 10 cm
 - Collaborative: ~ 3 cm

Iterative Weighted Multilateration



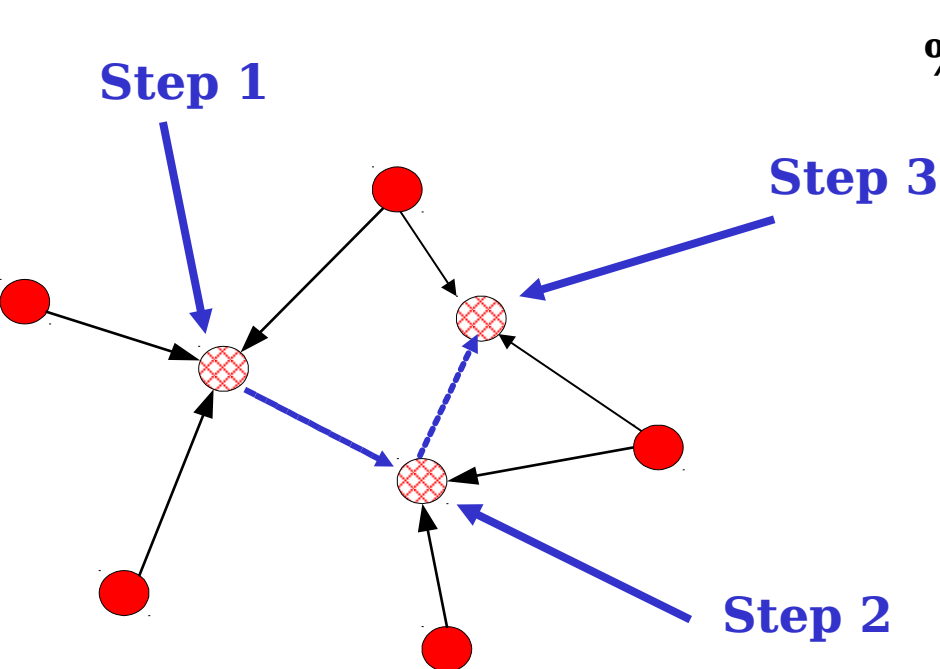
Collaborative Multilateration



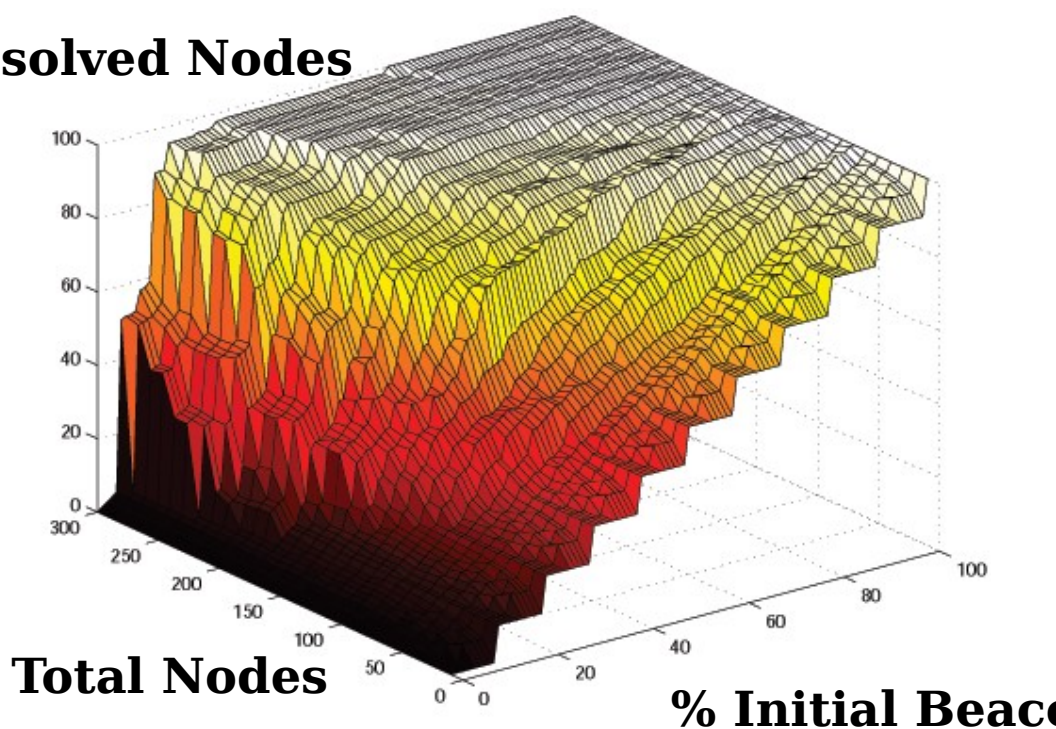


Iterative Multilateration

- **Atomic multilateration applied iteratively across the network**
 - may stall if network is sparse, % of beacons is low, terrain obstacles



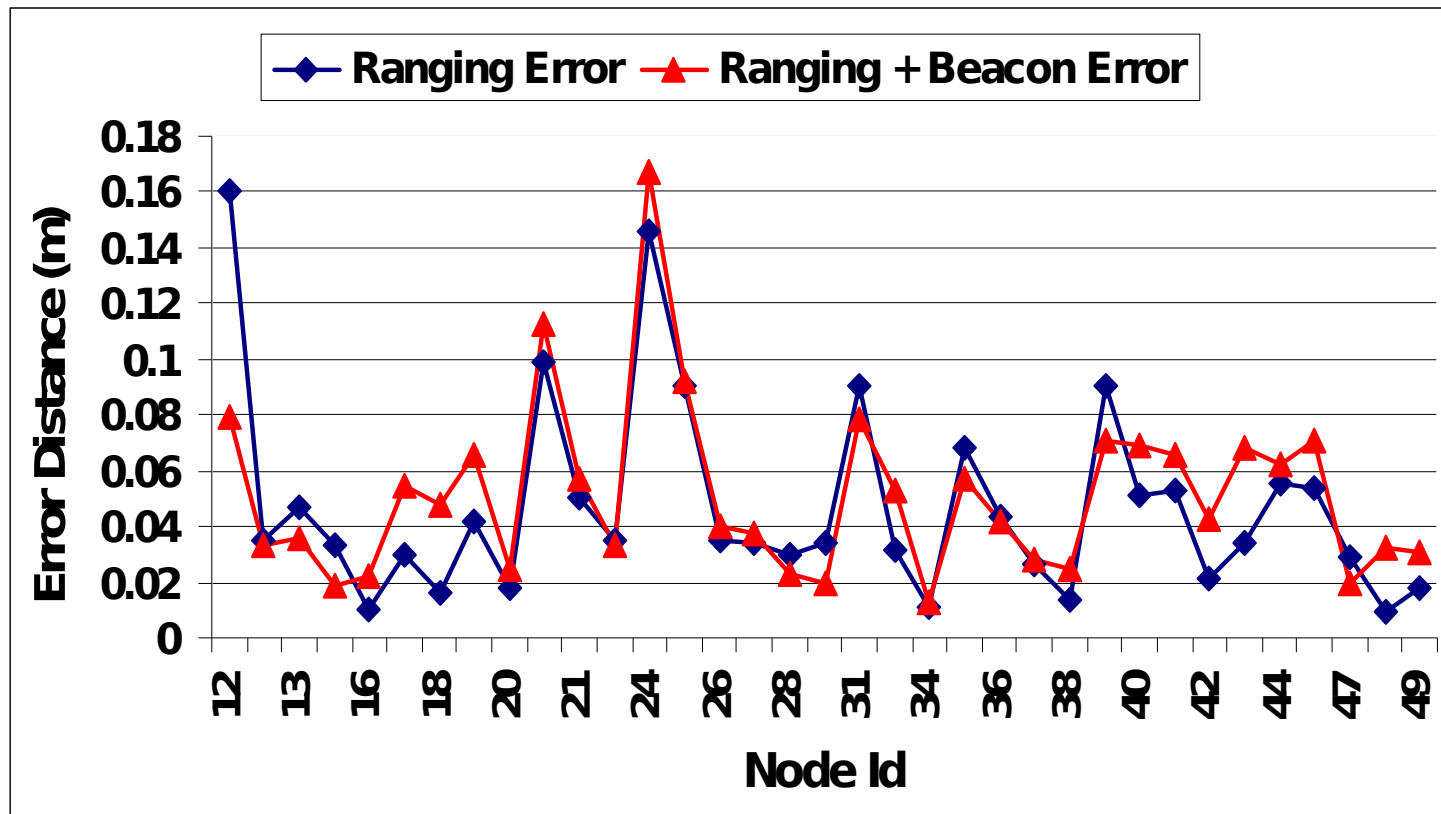
% Resolved Nodes



**Uniformly distributed
deployment in a field 100x100.
Node range = 10.**



Iterative Multilateration Accuracy

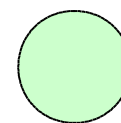
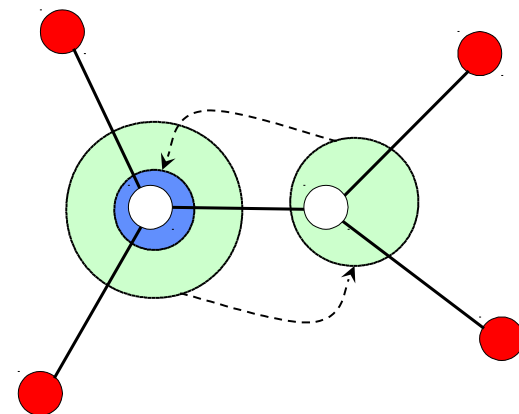
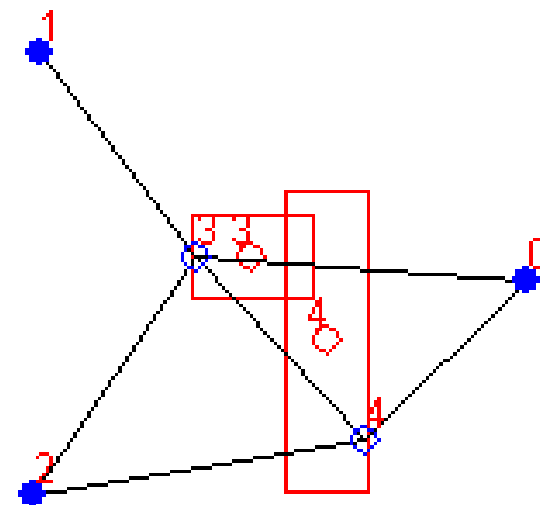


50 Nodes 10% beacons 20mm white gaussian ranging error



Collaborative Multilateration

- **Step 1: form “Collaborative Subtrees” within their neighborhood**
 - an unknown node is collaborative if it has at least 3 participating neighbors
 - a node is participating if it is either a beacon, or if it is an unknown node that is also participating
 - at each node at least one of its participating nodes are new to the set
 - at least one of the beacons used to determine the position of a node should not be collinear with the other beacons used to determine the node position
- **Step II: obtain initial location estimate for subsequent computation**
 - use beacon locations & hop distances to obtain approximate location bounds
- **Step III: perform computation**
 - Measurement Update part of Kalman Filter
 - Centralized, at a leader elected in the subtree
 - or, Fully Distributed
 - can start computing locations based on node connectivity and initial estimate



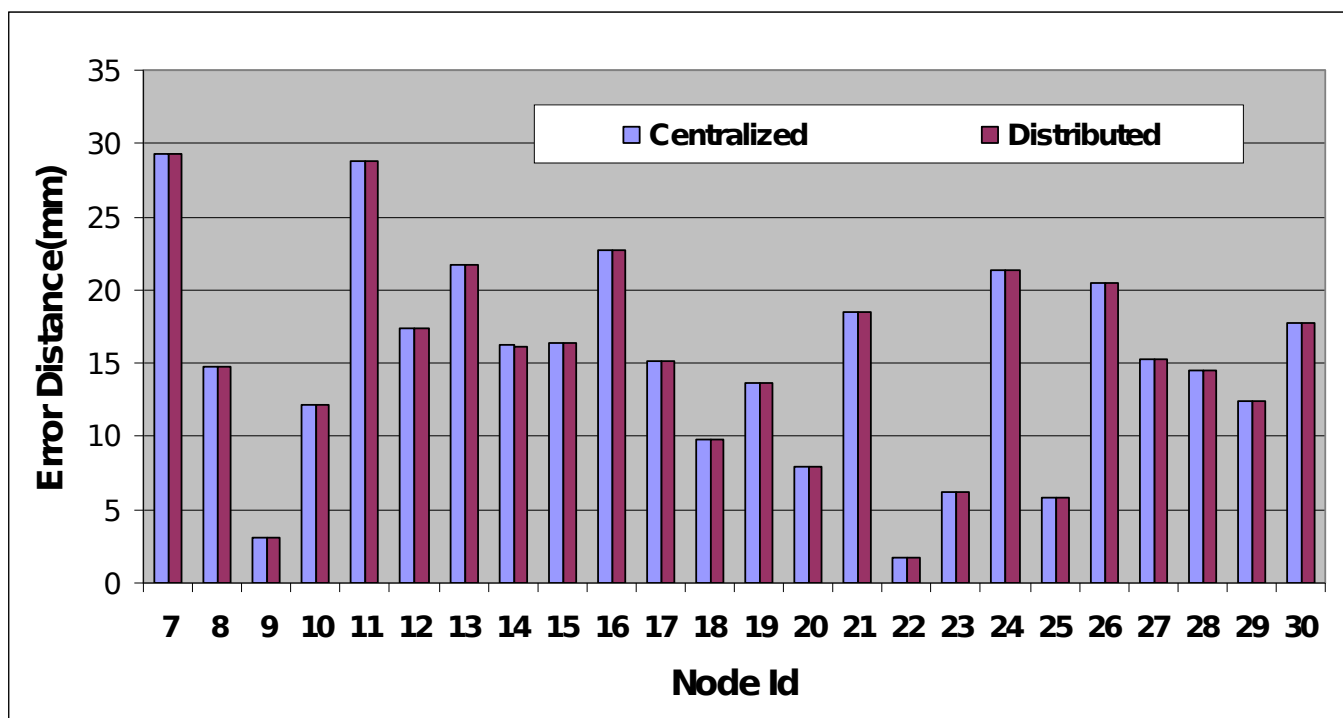
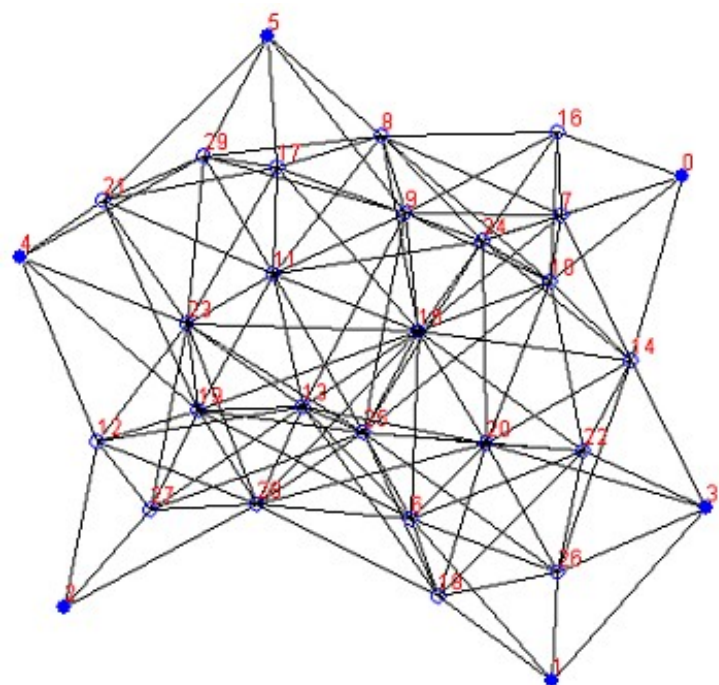
Uncertainty of estimate
location in first iteration



Uncertainty of estimate
location in second iteration



Example



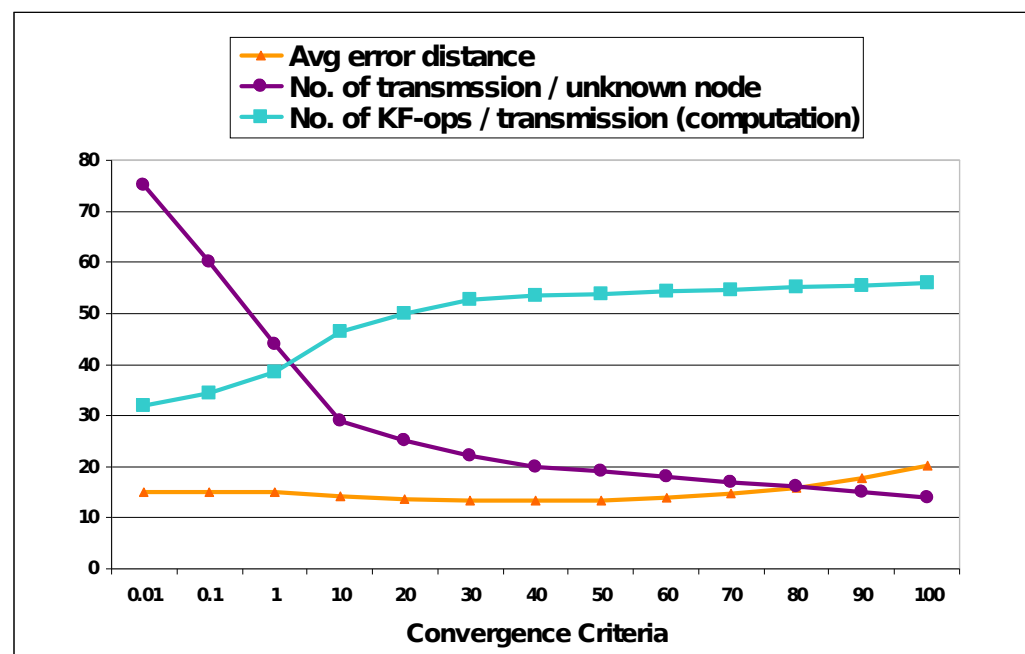
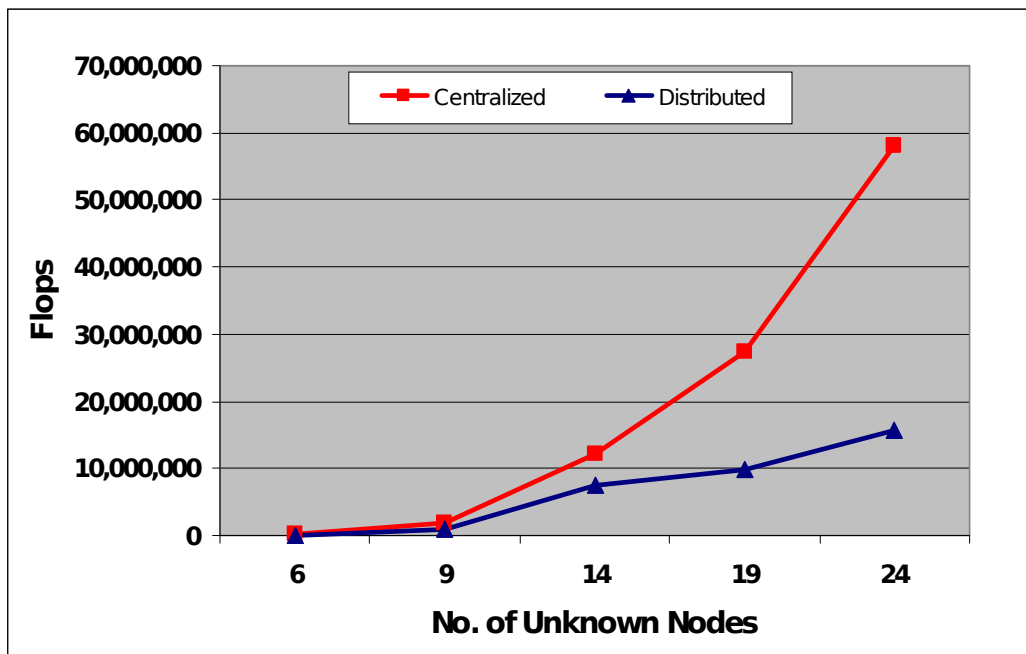
Network of 30 nodes

6 beacons, 24 unknowns

Ranging noise experimentally derived



Computation & Communication Expense



Computation Expense

Computation vs. Communication Tradeoff

Results using the FLOPS command in MATLAB

- **Total number of transmissions:**
 - Centralized 70 packets
 - Distributed 416 packets
- **Centralized approach has additional overhead for leader election**

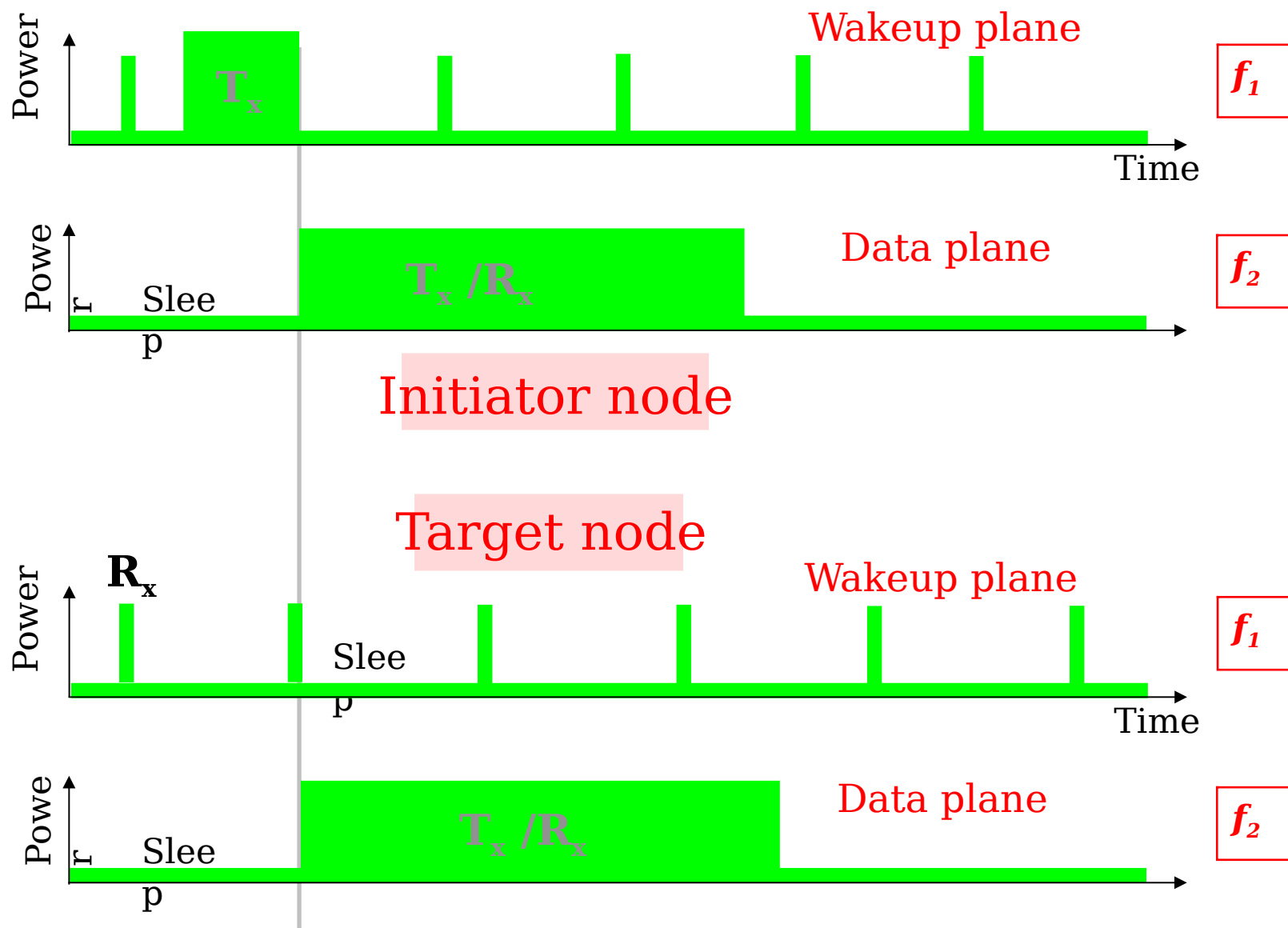


II. Topology Management

- **Two phases of sensor network operation**
 - Detect event
 - Relay information to users
- **Energy consumption of radio dominates that of sensors & CPU**
 - ⇒ perform event detection continuously
- **The only energy efficient mode of the radio is the sleep mode**
 - ⇒ put radio to sleep as often as possible
- **Existing approaches: density-energy trade-off**
 - keep enough nodes awake to handle the data forwarding (forwarding state)
 - but for substantial energy savings we need large densities
- **Observation**
 - most of the time, the network is only monitoring its environment, waiting for an event to happen (monitoring state)
- **Idea:**
 - put node radios to sleep and wake them up when they need to forward data
 - low duty-cycle paging channel using a 2nd radio: trades off **energy savings** for **setup latency**

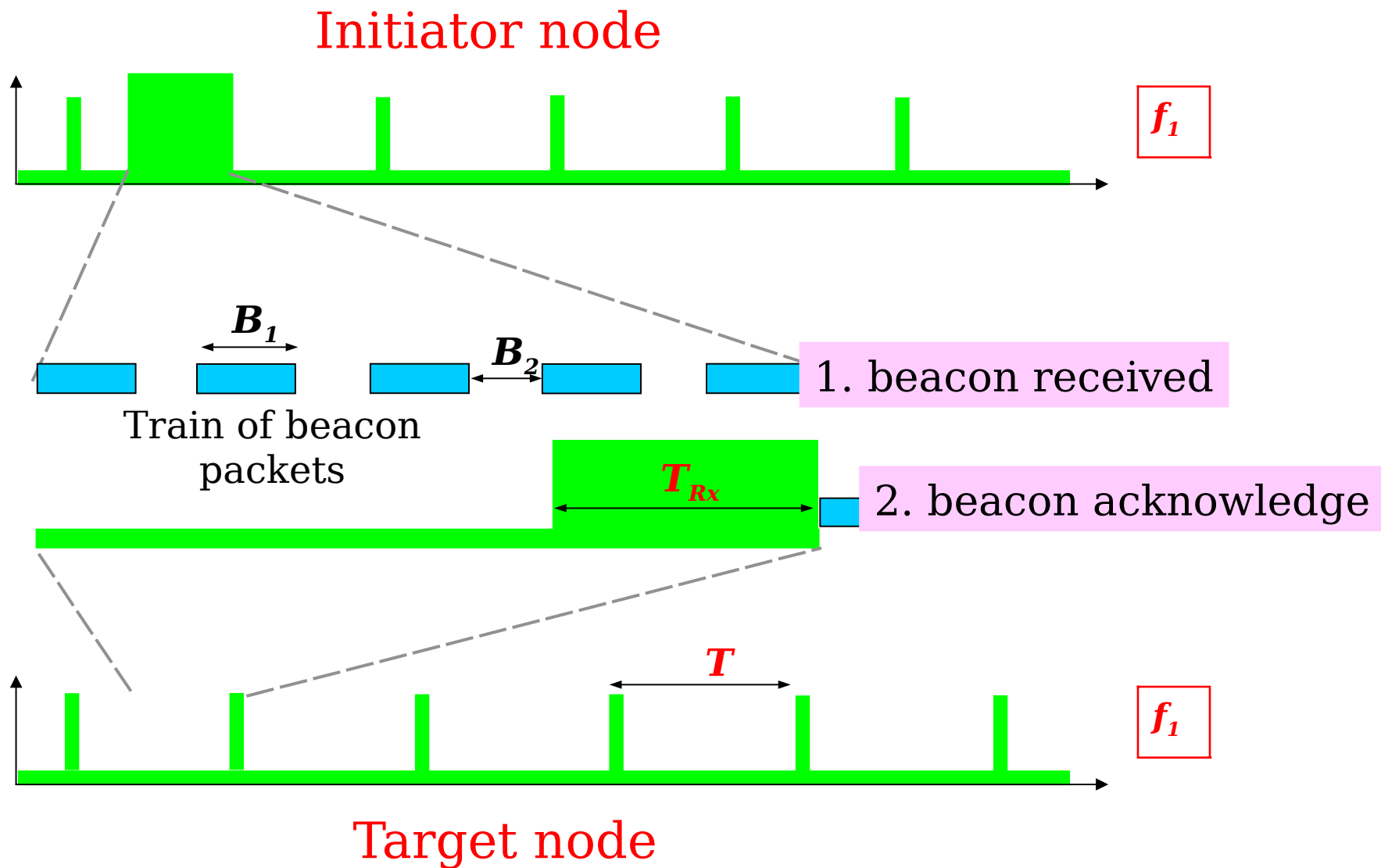


STEM: High-level Operation



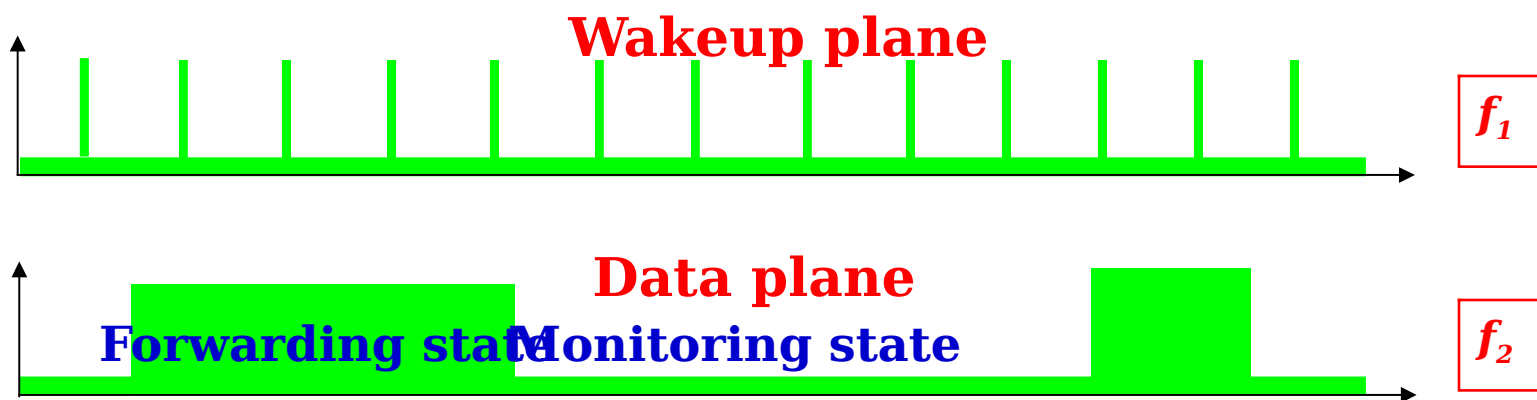


Detailed Operation





Latency - Energy Analysis



Fraction of time in the forwarding state: α

$$\beta = 1/\alpha$$

- Setup latency

$$\bar{T}_S \approx \frac{T + \frac{2}{3}T_{Rx}}{2}$$

Appropriate choice of interval sizes

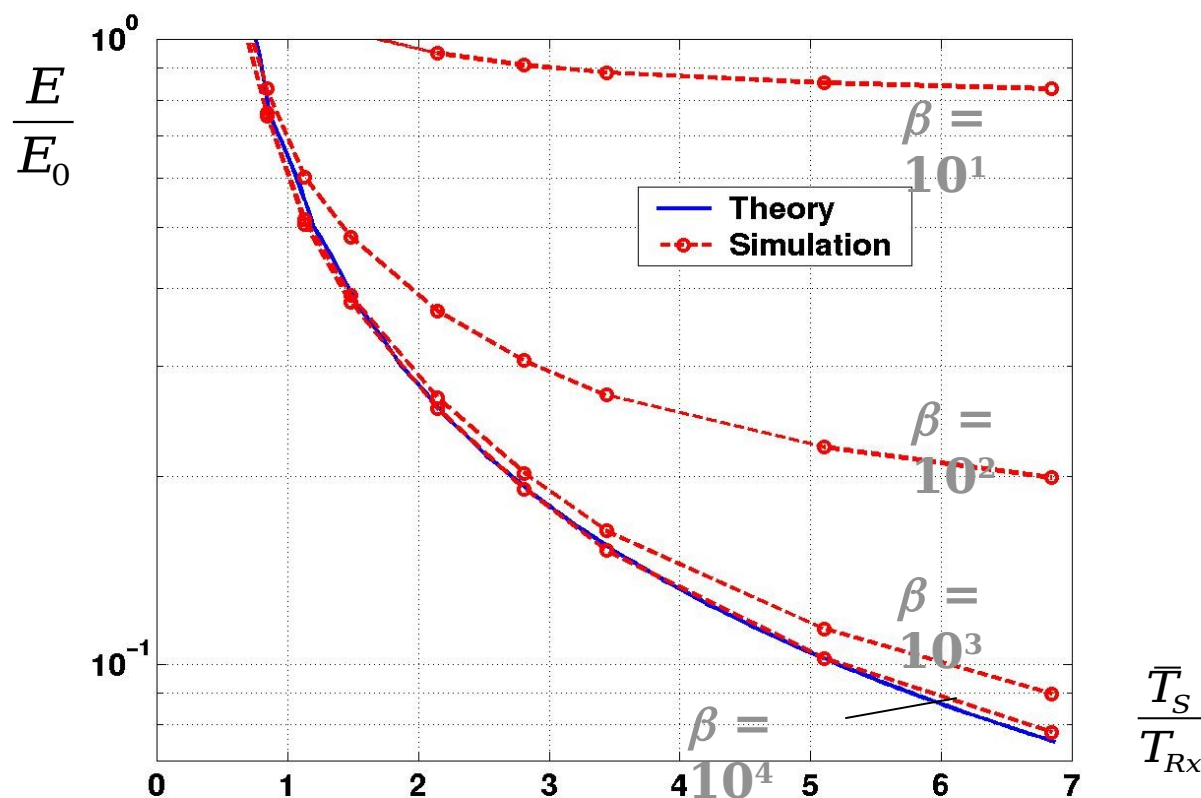
- Energy savings

$$\frac{E}{E_0} \approx \frac{T_{Rx}}{T}$$

Mostly monitoring state: $\alpha \ll 1$ or $\beta \gg 1$



Energy-Latency Trade-off



$$T_{Rx} = 0.225 \text{ s}$$

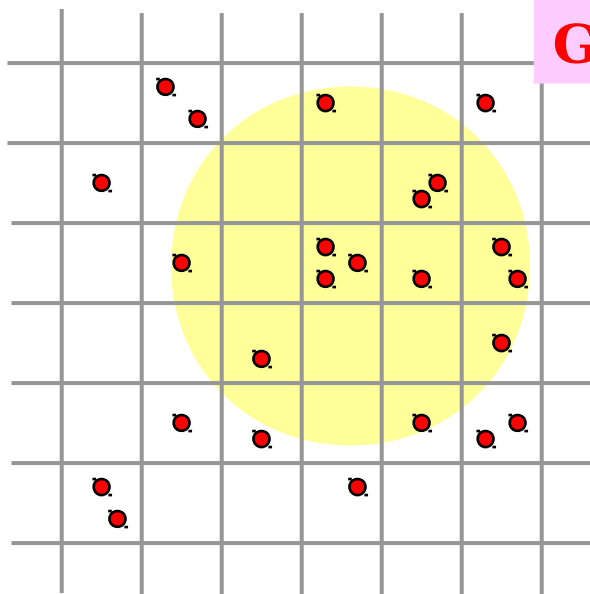
- The tradeoff between energy and delay is manipulated by varying T

$$T \uparrow \Rightarrow E \downarrow \quad T_S \uparrow$$

- The energy savings increase as the monitoring state becomes more dominant, $\beta \uparrow$



Topology Management in Forwarding State



GAF: Geographic Adaptive Fidelity [Ya2001]

- Conserve traffic forwarding capacity
- Divide network in virtual grids
- Each node in a grid is equivalent from a traffic forwarding perspective
- Keep **1 node awake in each grid** at a time

- GAF reduces the energy by a factor

M'

- This factor is a function of the **average** number of nodes in a grid:

$$M' = \frac{M}{1 - e^{-M}}$$

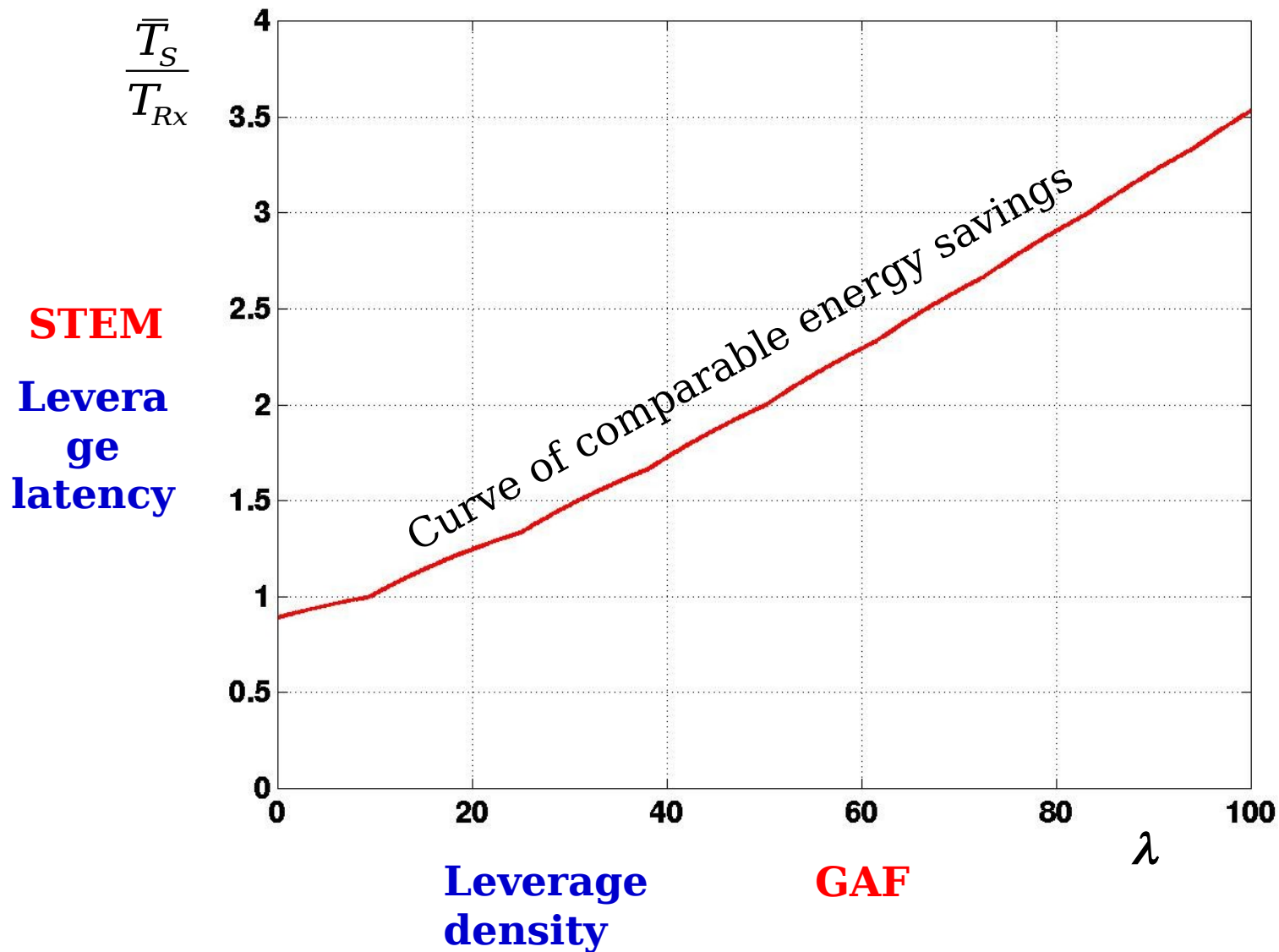
for uniformly random node deployment

M'	M	λ
1.0	0	0
1.5	0.8 7	13. 7
2.0	1.5 9	25. 0
2.5	2.2 2	35. 0
3.0	2.8 2	44. 3

Average number of neighbors of a node



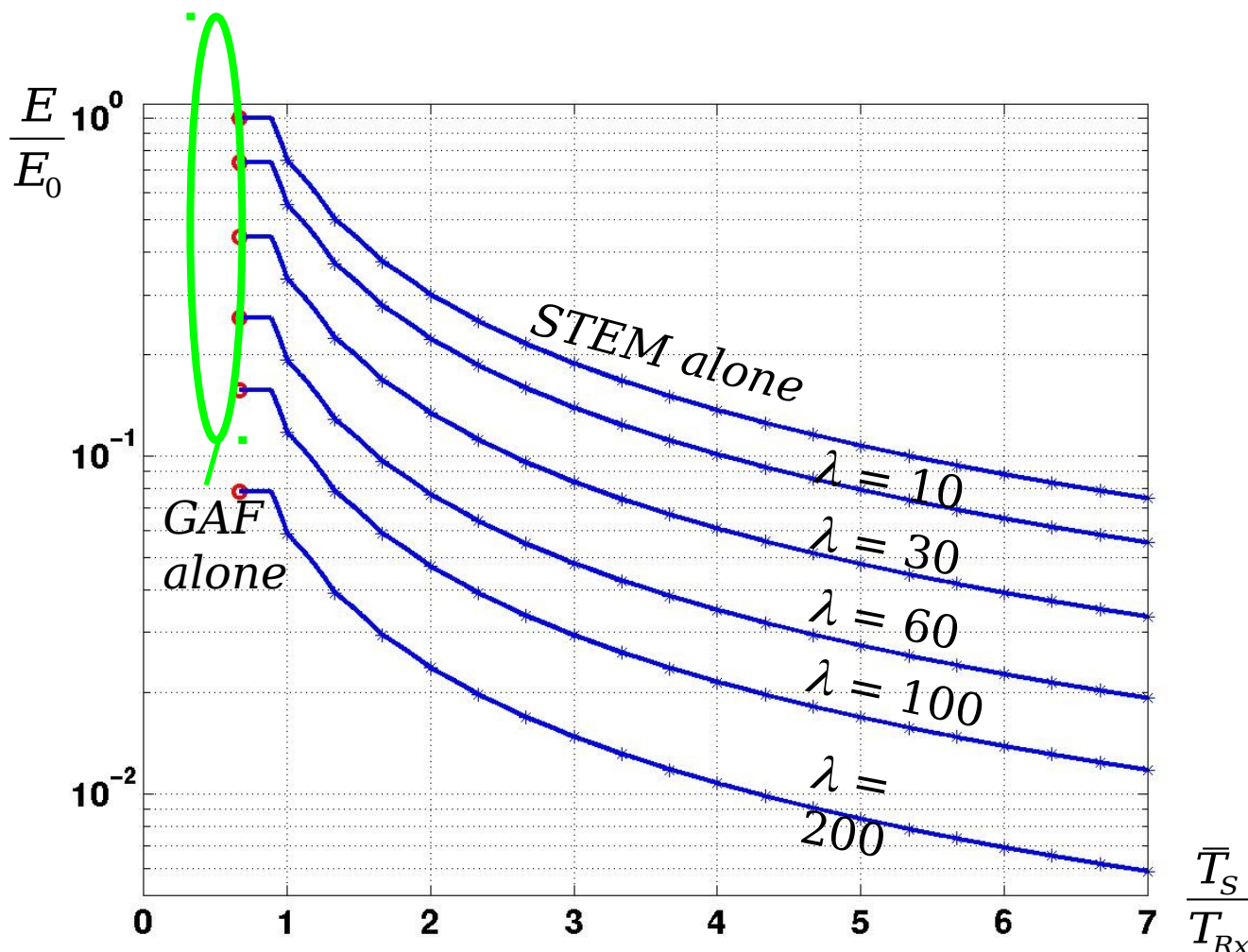
Comparing STEM & GAF





Combining STEM and GAF for Joint Energy-Latency-Density Trade-off

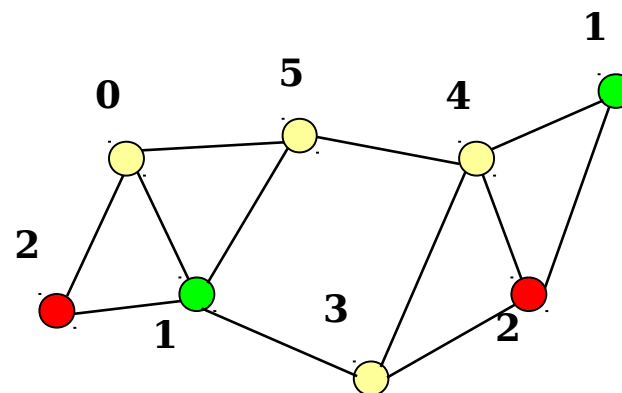
- As in GAF, 1 node is active in each grid
⇒ the grid can be considered a virtual node
- This virtual node runs the STEM protocol





III. Dynamic MAC Address Assignment

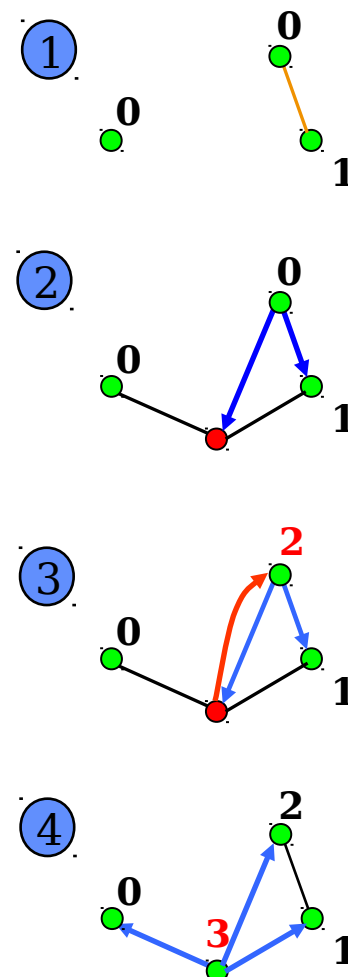
- **Wireless spectrum is broadcast medium**
- **MAC addresses are required**
- **In wireless sensor networks, data size is small**
- **Unique MAC address present unneeded overhead**
- **Employ spatial address reuse (similar to reuse in cellular systems)**
 - MAC address, link ids
- **Two aspects**
 - Dynamic assignment algorithm
 - Address representation





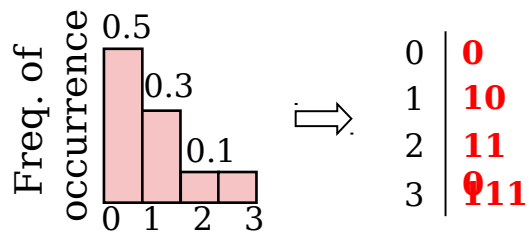
Distributed Assignment Algorithm

1. Network is operational (nodes have valid address)
 2. Listen to periodic **broadcasts** of neighboring nodes
 3. In case of conflict, **notify node**
 - (this node resends a **broadcast**)
 4. Choose non-conflicting address and **broadcast** address in a periodic cycle. At this point the new node has joined the network.
- *Additive convergence*: network remains operational during address selection
 - *Mapping*: unique ID to spatially reusable address
 - Algorithm also valid when unidirectional links





Encoded Address Representation

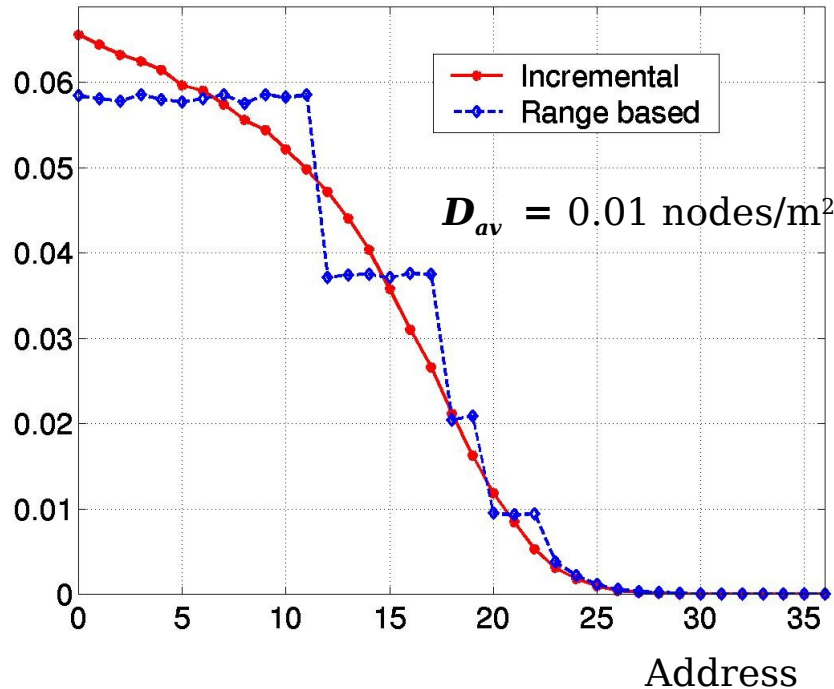


Encoded (bits/address)	1.7
Fixed size (bits/address)	2

- Size of the address field?
- Non-uniform address frequency
 - Huffman encoding
 - Robust: can represent any address
- Practical address selection
 - All addresses with same codeword size are equivalent
 - Choose random address in that range to reduce conflict messages

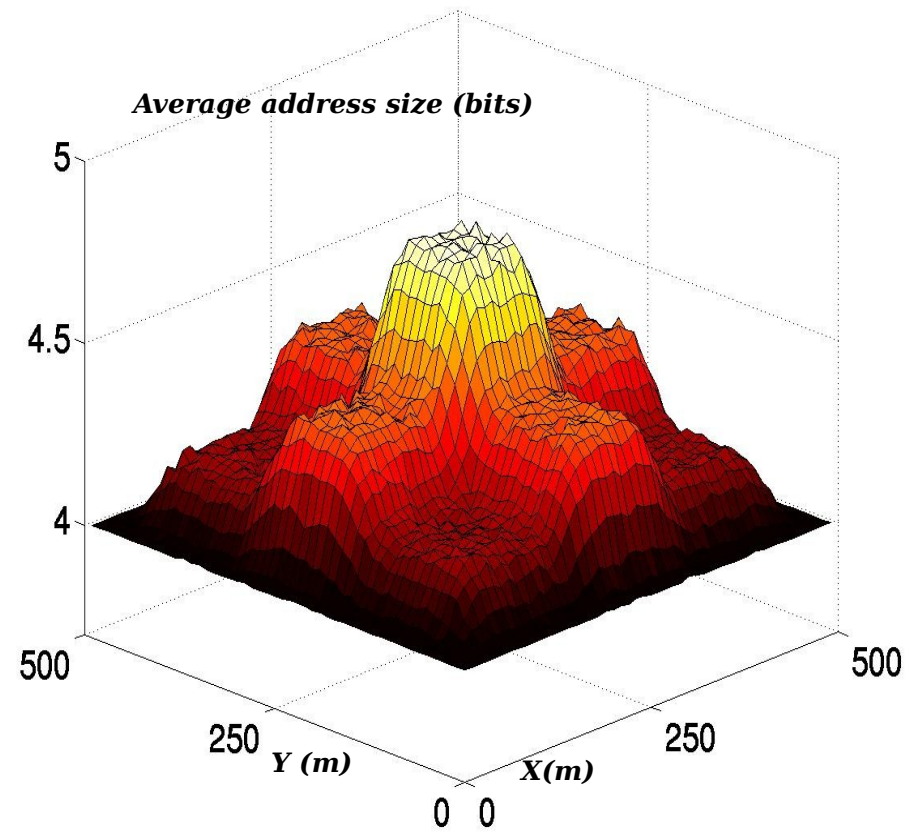
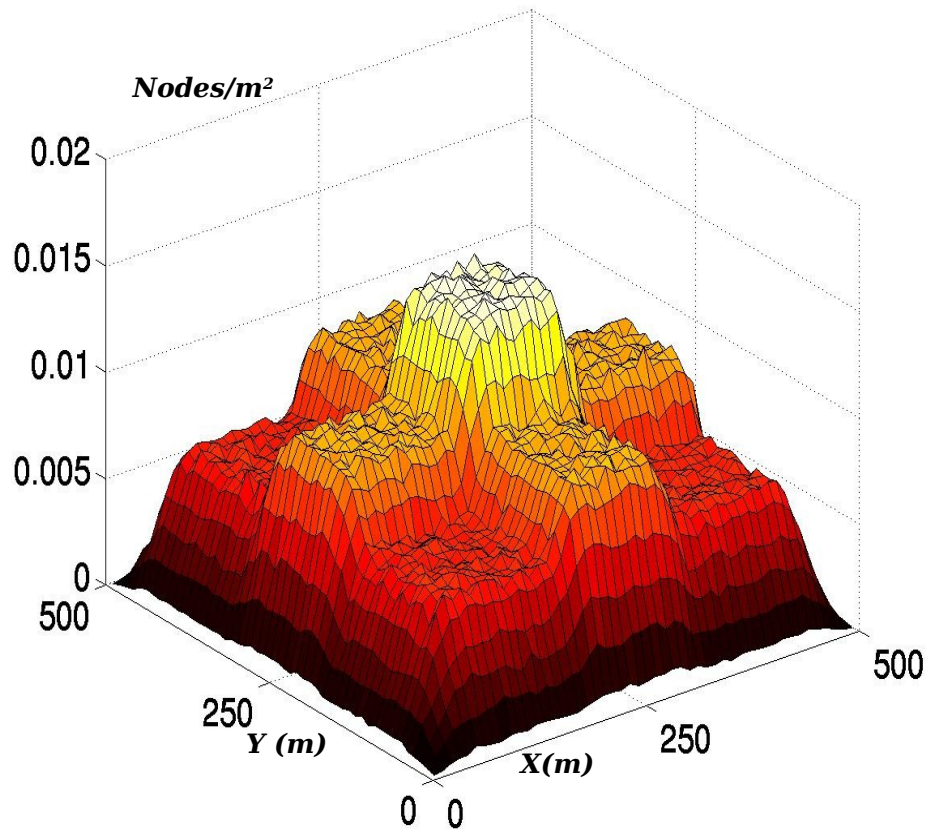
Address range	0-11	12-17	18-19	20-22	23	...
Codeword size (bits)	4	5	6	7	8	...

Frequency





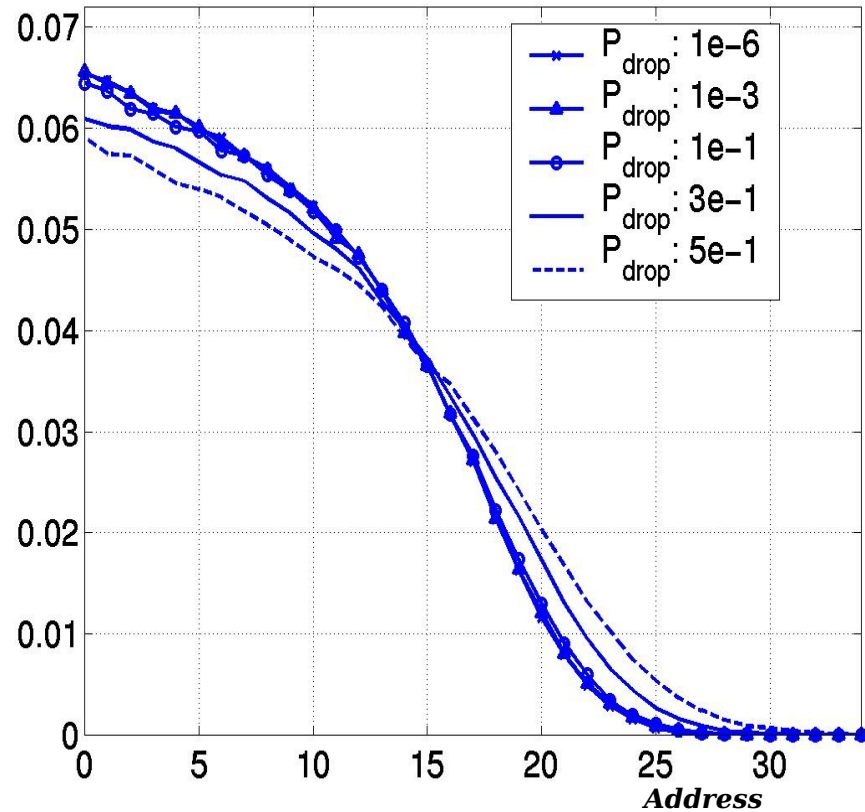
Non-uniform Network Density



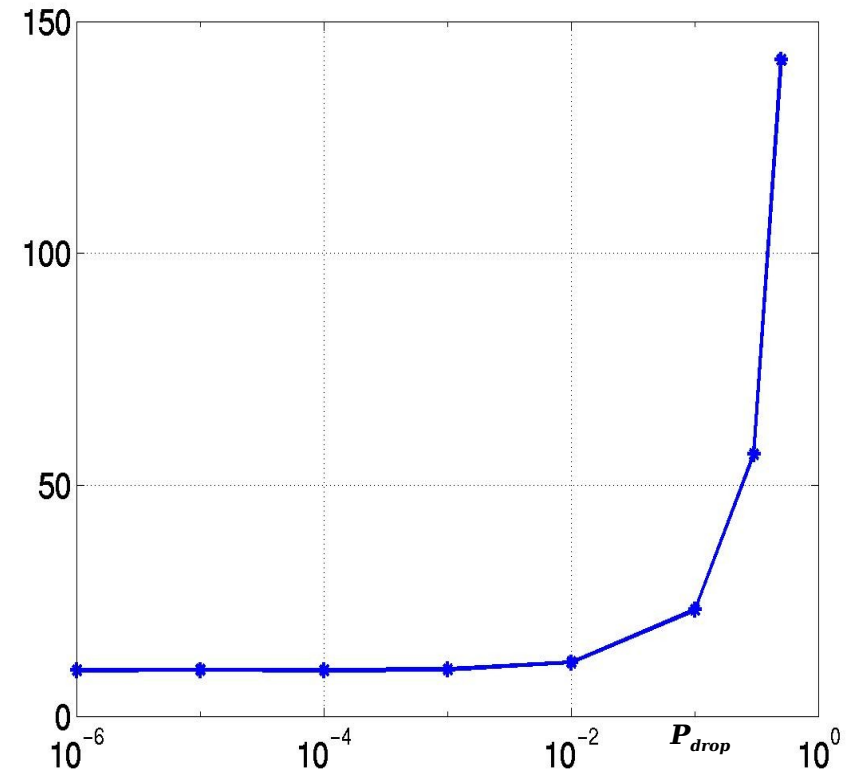


Effect of Packet Losses ($\lambda = 10$)

Frequency



Convergence time (s)



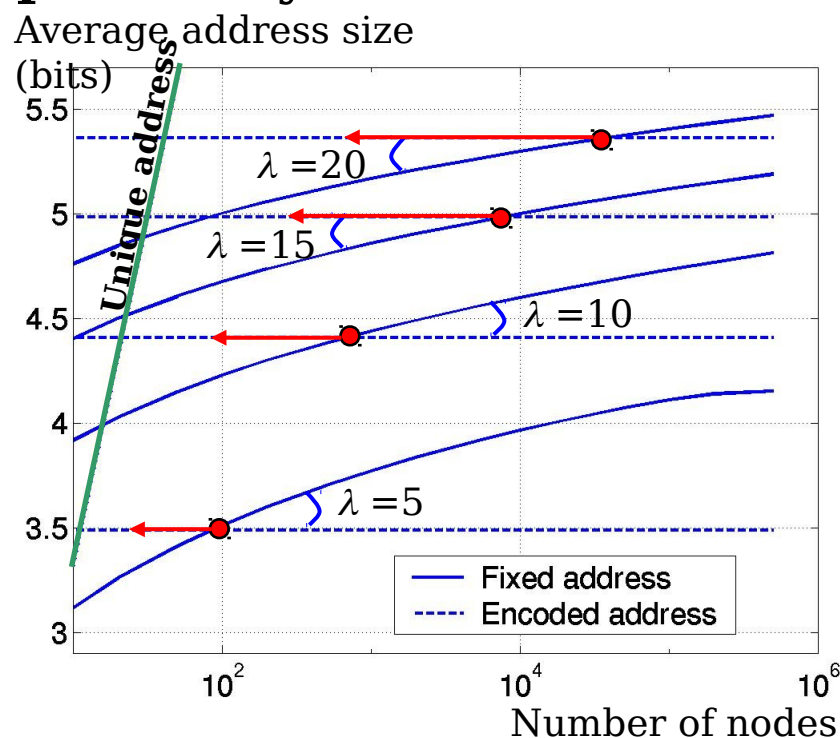
- **Address assignment**
 - **Distributed algorithm with periodic localized communication**
- **Address representation**
 - **Encoded addresses depend only on distribution**

Scales perfectly
(neglecting edge effects)

Representation assignment

Off-line	Centralized	Distributed
++	-	+

Unique	Fixed reusable	Encoded reusable
--	±	+





Simulation Results

Our
scheme
s

Scheme	Address selection n type	Av. size (bits)	Addres s size scalabil ity
Globally unique	Manufacturi ng	128	+
Network wide unique	Deployment	14	-
Fixed size dynamic	Centr. / Distr.	4.7	\pm
Encoded dynamic	Distributed	4.4	+



Dynamic Address Allocation: Summary

- **Spatial reuse of address**
- **Dynamic assignment algorithm**
 - **Localized: scalability**
 - **Additive convergence: robustness**
- **Encoded address representation**
 - **Independent of network size: scalability**
 - **Variable length addresses: robustness**

